Variable frequency drive, 400 V AC, 3 -phase, $30 \mathrm{~A}, 15 \mathrm{~kW}$, IP20/NEMA 0 , Brake chopper, braking transistor, FS4

Powering Business Worldwide"

## Part no. <br> DC1-34030FB-A20CE1 185780

| Product name | Eaton DC1 Variable frequency drive |
| :---: | :---: |
| Part no. | DC1-34030FB-A20CE1 |
| EAN | 4015081812790 |
| Product Length/Depth | 211 millimetre |
| Product height | 418.5 millimetre |
| Product width | 173 millimetre |
| Product weight | 8.4 kilogram |
| Certifications | EAC <br> UL 508C <br> UL report applies to both US and Canada <br> CUL <br> RoHS, ISO 9001 <br> Certified by UL for use in Canada <br> UL Category Control No.: NMMS, NMMS7 <br> Specification for general requirements: IEC/EN 61800-2 <br> RCM <br> IEC/EN61800-5 <br> CE <br> IEC/EN61800-3 <br> UkrSEPRO <br> UL <br> Safety requirements: IEC/EN 61800-5-1 <br> CSA-C22.2 No. 14 <br> UL File No.: E172143 <br> IEC/EN 61800-3 |
| Product Tradename | DC1 |
| Product Type | Variable frequency drive |
| Product Sub Type | None |
| Catalog Notes | Environmental class: 3C2, 3S2 <br> Overload cycle for 60 s every 600 s |
| Features | Parameterization: drivesConnect <br> Parameterization: drivesConnect mobile (App) <br> Parameterization: Fieldbus <br> Parameterization: Keypad |
| Fitted with: | IGBT inverter <br> 7-digital display assembly <br> Internal DC link <br> PC connection <br> Control unit <br> Brake chopper <br> Breaking resistance <br> Additional PCB protection <br> Radio interference suppression filter |
| Functions | 4-quadrant operation possible |
| Cable length | 100 m , screened, maximum permissible, Motor feeder C2 $\leq 5 \mathrm{~m}$, Radio interference level, maximum motor cable length 300 m , unscreened, with motor choke, maximum permissible, Motor feeder 200 m , screened, with motor choke, maximum permissible, Motor feeder 150 m , unscreened, maximum permissible, Motor feeder $\mathrm{C} 3 \leq 25 \mathrm{~m}$, Radio interference level, maximum motor cable length |
| Communication interface | OP-Bus (RS485), built in SmartWire-DT, optional CANopen ${ }^{\circledR}$, built in Modbus RTU, built in |
| Connection to SmartWire-DT | Yes <br> In conjunction with DX-NET-SWD3 SmartWire DT module |
| Degree of protection | IP20 <br> NEMA Other |
| Electromagnetic compatibility | 1st and 2nd environments (according to EN 61800-3) |
| Frame size | FS4 |
| Mounting position | Vertical |



| Assigned motor current IM at $115 \mathrm{~V}, 50 \mathrm{~Hz}, 150 \%$ overload | 30 A |
| :---: | :---: |
| Assigned motor current IM at $220-240 \mathrm{~V}, 60 \mathrm{~Hz}, 150 \%$ overload | 30 A |
| Assigned motor current IM at $230 \mathrm{~V}, 50 \mathrm{~Hz}, 150 \%$ overload | 30 A |
| Assigned motor current IM at $400 \mathrm{~V}, 50 \mathrm{~Hz}, 150 \%$ overload | 30 A |
| Assigned motor current IM at $440-480 \mathrm{~V}, 60 \mathrm{~Hz}, 150 \%$ overload | 30 A |
| Assigned motor power at $115 / 120 \mathrm{~V}, 60 \mathrm{~Hz}, 1$-phase | 20 HP |
| Assigned motor power at $230 / 240 \mathrm{~V}, 60 \mathrm{~Hz}, 1$-phase | 20 HP |
| Assigned motor power at $460 / 480 \mathrm{~V}, 60 \mathrm{~Hz}$ | 20 HP |
| Assigned motor power at $460 / 480 \mathrm{~V}, 60 \mathrm{~Hz}, 3$-phase | 20 HP |
| Apparent power at 400 V | $12 \mathrm{kV} \cdot \mathrm{A}$ |
| Apparent power at 480 V | $14.4 \mathrm{kV} \cdot \mathrm{A}$ |
| Braking resistance | 300 |
| Braking torque | Max. $100 \%$ of rated operational current le, variable, DC - Main circuit |
| Switch-on threshold for the braking transistor | 780 V DC |
| Number of inputs (analog) | 2 (parameterizable, 0-10V DC, $0 / 4-20 \mathrm{~mA}$ ) |
| Number of inputs (digital) | 4 (parameterizable, 10-30 V DC) |
| Number of outputs (analog) | 1 |
| Number of outputs (digital) | 1 |
| Number of relay outputs | 1 (parameterizable, $\mathrm{N} / 0,6 \mathrm{~A}(250 \mathrm{~V}, \mathrm{AC}-1) / 5 \mathrm{~A}(30 \mathrm{~V}, \mathrm{DC}-1)$ ) |
| Equipment heat dissipation, current-dependent Pvid | 607 W |
| Heat dissipation capacity Pdiss | OW |
| Heat dissipation per pole, current-dependent Pvid | OW |
| Rated operational current for specified heat dissipation (In) | 30 A |
| Static heat dissipation, non-current-dependent Pvs | OW |
| Heat dissipation details | Operation (with $150 \%$ overload) |
| 10.2.2 Corrosion resistance | Meets the product standard's requirements. |
| 10.2.3.1 Verification of thermal stability of enclosures | Meets the product standard's requirements. |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat | Meets the product standard's requirements. |
| 10.2.3.3 Resist. of insul. mat. to abnormal heat/fire by internal elect. effects | Meets the product standard's requirements. |
| 10.2.4 Resistance to ultra-violet (UV) radiation | Meets the product standard's requirements. |
| 10.2.5 Lifting | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 Mechanical impact | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 Inscriptions | Meets the product standard's requirements. |
| 10.3 Degree of protection of assemblies | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 Clearances and creepage distances | Meets the product standard's requirements. |
| 10.5 Protection against electric shock | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.6 Incorporation of switching devices and components | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 Internal electrical circuits and connections | Is the panel builder's responsibility. |
| 10.8 Connections for external conductors | Is the panel builder's responsibility. |
| 10.9.2 Power-frequency electric strength | Is the panel builder's responsibility. |
| 10.9.3 Impulse withstand voltage | Is the panel builder's responsibility. |
| 10.9.4 Testing of enclosures made of insulating material | Is the panel builder's responsibility. |
| 10.10 Temperature rise | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.12 Electromagnetic compatibility | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.13 Mechanical function | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed. |

## Technical data ETIM 8.0

Low-voltage industrial components (EG000017) / Frequency converter $=<1 \mathrm{kV}$ (EC001857)

Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014])

| Mains voltage | V | 380-480 |
| :---: | :---: | :---: |
| Mains frequency |  | $50 / 60 \mathrm{~Hz}$ |
| Number of phases input |  | 3 |
| Number of phases output |  | 3 |
| Max. output frequency | Hz | 500 |
| Max. output voltage | v | 500 |
| Nominal output current 12N | A | 30 |
| Max. output at quadratic load at rated output voltage | kW | 15 |
| Max. output at linear load at rated output voltage | kW | 15 |
| Relative symmetric net frequency tolerance | \% | 10 |
| Relative symmetric net voltage tolerance | \% | 10 |
| Number of analogue outputs |  | 1 |
| Number of analogue inputs |  | 2 |
| Number of digital outputs |  | 1 |
| Number of digital inputs |  | 4 |
| With control element |  | Yes |
| Application in industrial area permitted |  | Yes |
| Application in domestic- and commercial area permitted |  | Yes |
| Supporting protocol for TCP/IP |  | No |
| Supporting protocol for PROFIBUS |  | No |
| Supporting protocol for CAN |  | Yes |
| Supporting protocol for INTERBUS |  | No |
| Supporting protocol for ASI |  | No |
| Supporting protocol for KNX |  | No |
| Supporting protocol for Modbus |  | Yes |
| Supporting protocol for Data-Highway |  | No |
| Supporting protocol for DeviceNet |  | No |
| Supporting protocol for SUCONET |  | No |
| Supporting protocol for LON |  | No |
| Supporting protocol for PROFINET IO |  | No |
| Supporting protocol for PROFINET CBA |  | No |
| Supporting protocol for SERCOS |  | No |
| Supporting protocol for Foundation Fieldbus |  | No |
| Supporting protocol for EtherNet/IP |  | Yes |
| Supporting protocol for AS-Interface Safety at Work |  | No |
| Supporting protocol for DeviceNet Safety |  | No |
| Supporting protocol for INTERBUS-Safety |  | No |
| Supporting protocol for PROFIsafe |  | No |
| Supporting protocol for SafetyBUS p |  | No |
| Supporting protocol for BACnet |  | No |
| Supporting protocol for other bus systems |  | Yes |
| Number of HW-interfaces industrial Ethernet |  | 0 |
| Number of interfaces PROFINET |  | 0 |
| Number of HW-interfaces RS-232 |  | 0 |
| Number of HW-interfaces RS-422 |  | 0 |
| Number of HW-interfaces RS-485 |  | 1 |
| Number of HW-interfaces serial TTY |  | 0 |
| Number of HW-interfaces USB |  | 0 |
| Number of HW-interfaces parallel |  | 0 |
| Number of HW-interfaces other |  | 0 |
| With optical interface |  | No |
| With PC connection |  | Yes |
| Integrated breaking resistance |  | Yes |
| 4-quadrant operation possible |  | Yes |

Degree of protection (IP)
Degree of protection (NEMA) Other

Height
mm 211

